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EMBEDDING TECHNOLOGY



Integration Opportunities in Automotive Infotainment Systems

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agenda

- (brief) Evidence company profile
- trends in integrated automotive electronics
- some details on ERIKA Enterprise
- SCHED_DEADLINE in Infotainment systems
- conclusions

Evidence

company profile

the company

Founded in 2002 as spin-off company of the
Real-Time Systems Lab at Scuola Superiore S.Anna



~20 qualified people with an average age of 34 years

10+ years of experience in academic and industrial projects

One third of the company has a PhD degree

Our Mission:

design and development software for small electronic devices



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products and services



open source OSEK/VDX RTOS and IDE



simulation and code generation tool
based on open-source tools



BSP/SDK for Embedded Linux systems
Custom drivers

application development
on various platforms



Let's start!

The basic idea...

Automotive embedded systems changed over time

- 1985 – Isolated embedded architectures
- 1995 – Distributed architectures over CAN bus
- 2005 – Integrated architectures based on AUTOSAR
- 2015 – Distributed architectures based on
Multicore AUTOSAR + Infotainment solutions



What's next?

...is cost reduction

- 2025 – Distributed architectures ...
...with small number of nodes

Need to:

- Integrate applications from different sources → **AUTOSAR components**
- Integrate applications with heterogeneous timing requirements → **schedulability analysis**
- Integrate applications with different safety levels → **mixed criticality, mem. protection**

... but then...

- Integrate applications with different semantics → ???

A **static** world...

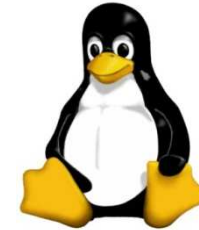
- Static allocation of resources, Static software architecture, control
- No dynamic allocation of memory
- Hard realtime, safety critical
- Limited HW resources

Compared with a **dynamic** world:

- Infotainment has relaxed real-time constraints
- Works on Linux-based systems (or similar)
- GUI, Network, Graphical libraries, standard applications
- iPhone/Android integration, App stores

the “dynamic” side: Linux in infotainment

Many new infotainment systems on car
are based on Linux and Android



Automotive Grade Linux - <http://www.linuxfoundation.org>

Tizen - <https://www.tizen.org>

Genivi - <http://www.genivi.org/>



ok, Linux is there... but...

How can we implement the static part of the application integrating it with Linux?

Objectives:

- a **complete open-source solution**
 - ERIKA Enterprise as the underlying automotive RTOS
- **integrate** Linux with ERIKA preserving real-time performance
 - interrupt latency
 - fast boot
 - response time and scheduling algorithms

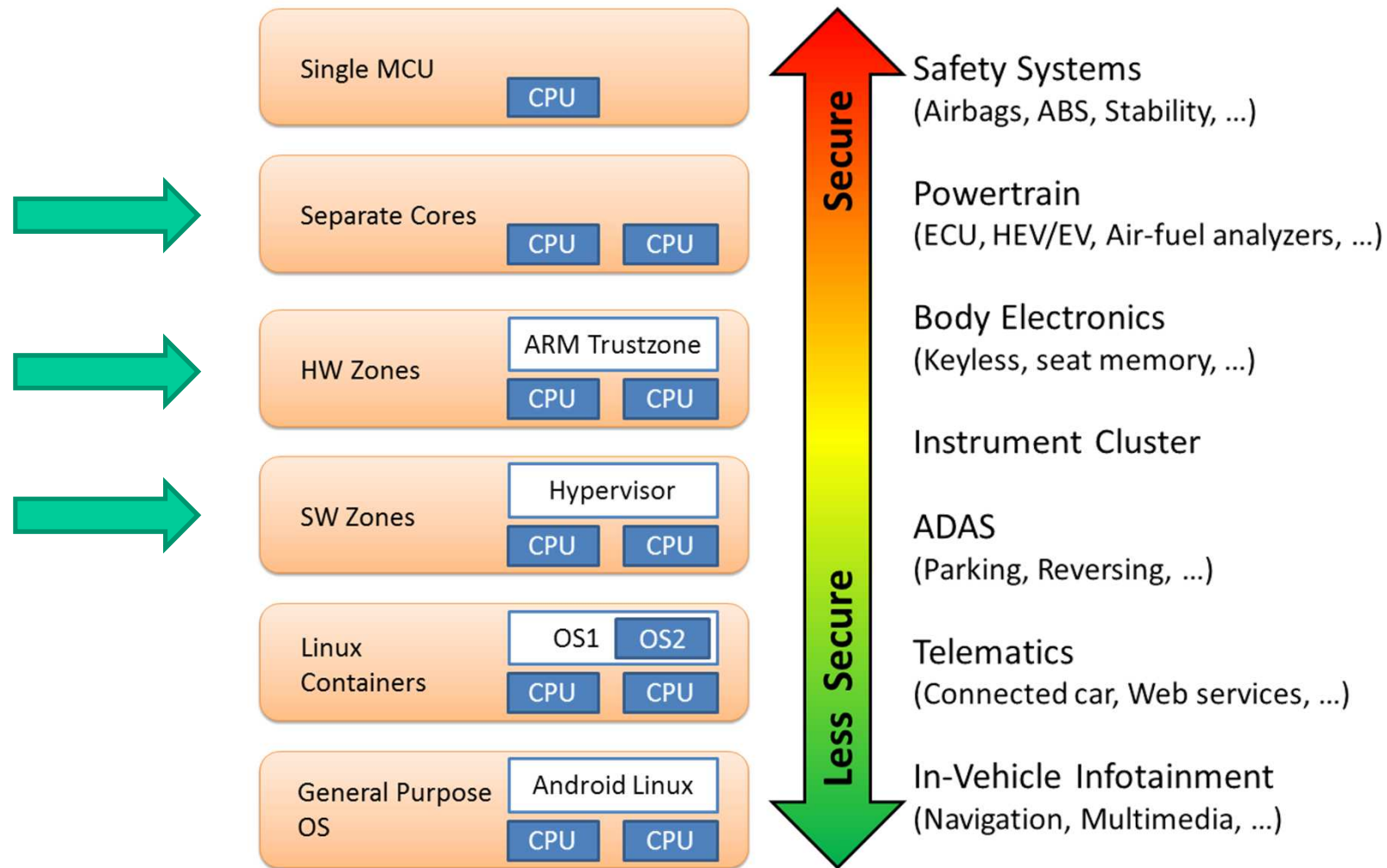
quick look at ERIKA Enterprise



<http://erika.tuxfamily.org>

- ERIKA Enterprise is an **OSEK/VDX certified** RTOS
- ERIKA Enterprise implements an API inspired by the **AUTOSAR OS API**
- offers a suitable **open-source license** allowing the **static linking** of closed source code
- Typical footprint around 2-4KB Flash
- Used by several automotive/white goods companies

Integration at different levels...



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Original source: Mentor Graphics,
Automotive Linux Conference Oct 2013

Current (and future) solutions

We worked on different directions:

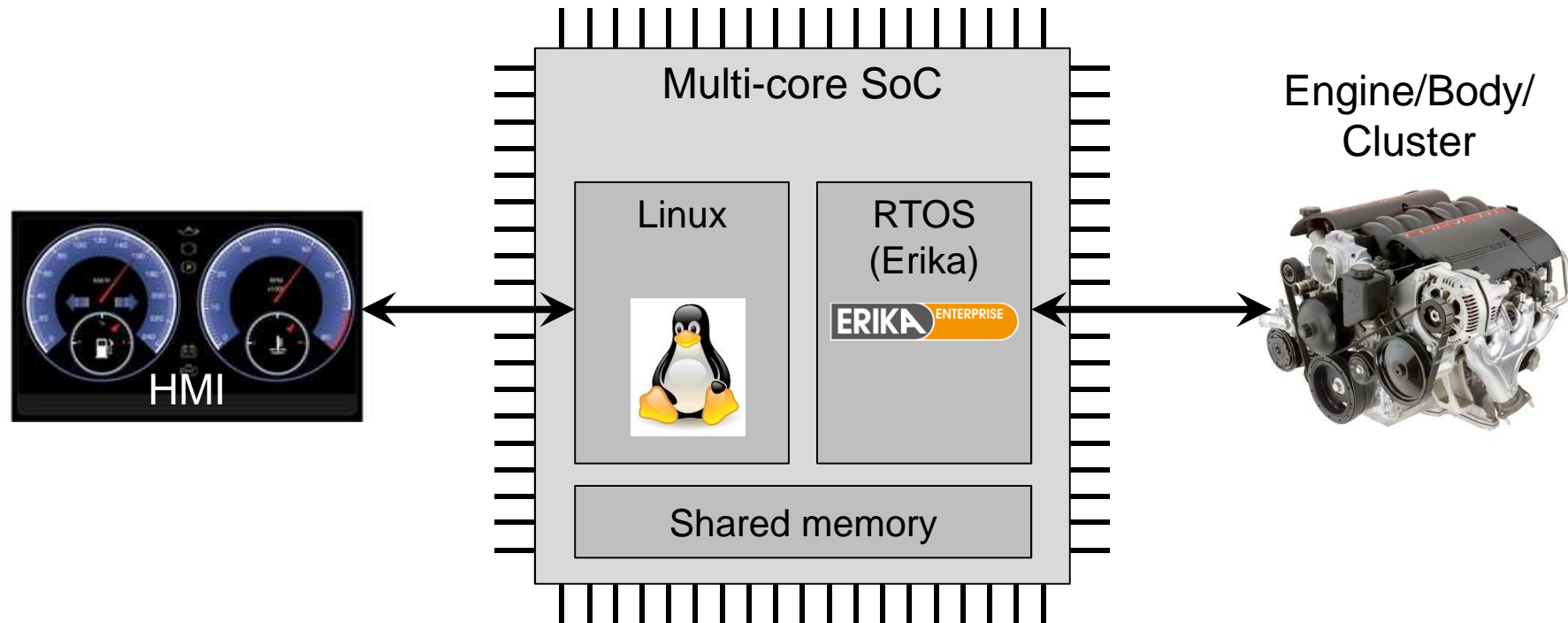
Available as a demo:

- Linux + ERIKA on **SMP cores** (iMX6)
- Linux + ERIKA on top of the **XEN** Hypervisor (as domU)

Linux + ERIKA on SMP multicores

Real-time and quality of service for IVI systems without hypervisor!

- ERIKA running on one core
- Linux on the second core



conclusions – open question...

Can SCHED_DEADLINE be used to schedule Hypervisor domains, or application subsets creating a timing isolation that allows to safely simplify the integration of different real-time/non-realtime applications on the same machine?

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