

# *Multi-Processor Real-Time Virtual Machines*

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# Multi-CPU VMs

- What about multiple CPUs?
  - Much more complex problem...
  - How to schedule the VMs on multiple CPUs?
  - Which local scheduler for multi-CPU VMs?
- How to model multi-CPU VMs?
  - Simplest (but pessimistic) solution: a supply function per CPU
- How to perform the schedulability analysis?
  - Depends on the (local and/or root) scheduler
- Multi-processor scheduling strategies: global vs partitioned

# Multi-CPU Schedulers

- Root scheduler model:
  - Multi Supply Function, Multi-Processor Resource model (MPR), Parallel Supply Function (PSF), ...
  - MSF: Pessimistic, because the worst cases often cannot happen simultaneously
  - MPR: Again, pessimistic (does not specify how the runtime is distributed between cores)
  - PSF: much less pessimistic, but **difficult to use**
- MPR is strictly tied to global scheduling in the guest
- PSF is much more generic...
- What about MSF? Depends on the local scheduler

# MSF And the Guest Scheduler

- MSF supports both global scheduling and partitioned scheduling in the guest
  - Global EDF (or Global FP) analysis...
  - Compute a (pessimistic) workload and compare it with the multi supply function
- Partitioned scheduling in the guest is also possible
  - Consider the tasks assigned to a virtual CPU...
  - ...Compute their dbf (or workload)...
  - ...And compare it with the sbf of the virtual CPU!!!
- This is all cool, but... What does “global scheduling” or “partitioned scheduling” mean?
- Let's see... **Multi-processor real-time scheduling in less than 10 slides!**

# Multiprocessor Scheduling

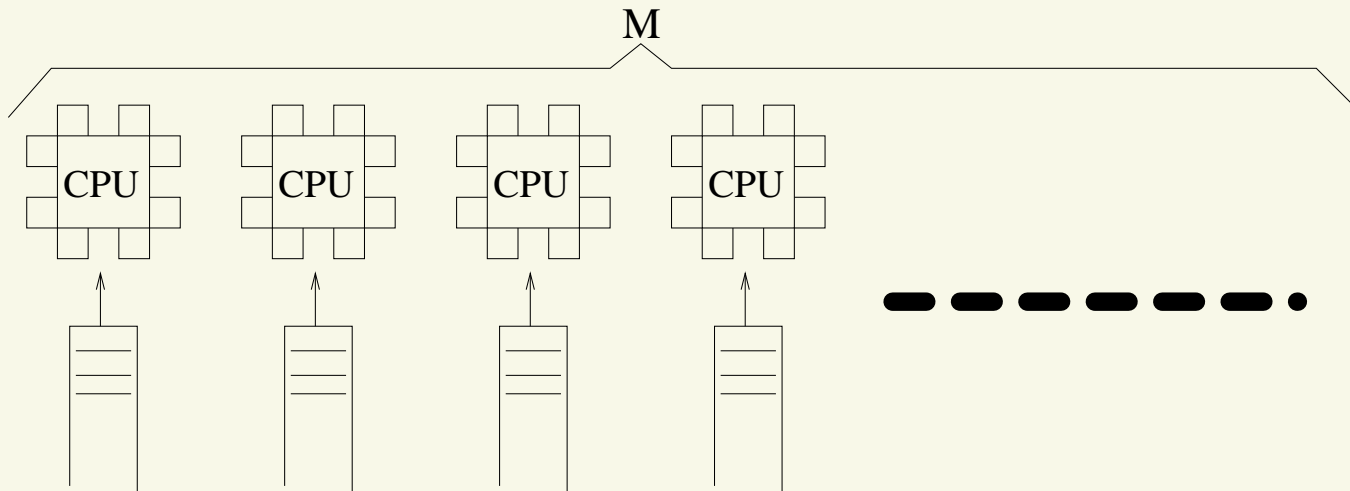
- UniProcessor Systems
  - A schedule  $\sigma(t)$  is a function mapping time  $t$  into an executing task  $\sigma : t \rightarrow \mathcal{T} \cup \{\tau_{idle}\}$  where  $\mathcal{T}$  is the set of tasks running in the system
  - $\tau_{idle}$  is the *idle task*
- For a multiprocessor system with  $M$  CPUs,  $\sigma(t)$  is extended to map  $t$  in vectors  $\tau \in (\mathcal{T} \cup \{\tau_{idle}\})^M$
- Scheduling algorithms for  $M > 1$  processors?
  - Partitioned scheduling
  - Global scheduling

# The Quest for Optimality

- UP Scheduling:
  - $N$  periodic tasks with  $D_i = T_i$ :  $(C_i, T_i, T_i)$
  - Optimal scheduler: if  $\sum \frac{C_i}{T_i} \leq 1$ , then the task set is schedulable
  - EDF is optimal
- Multiprocessor scheduling:
  - Goal: schedule periodic task sets with  $\sum \frac{C_i}{T_i} \leq M$
  - Is this possible?
  - Optimal algorithms

# Partitioned Scheduling - 1

- Reduce  $\sigma : t \rightarrow (\mathcal{T} \cup \{\tau_{idle}\})^M$  to  $M$  uniprocessor schedules  $\sigma_p : t \rightarrow \mathcal{T} \cup \{\tau_{idle}\}$ ,  $0 \leq p < M$ 
  - Statically assign tasks to CPUs
  - Reduce the problem of scheduling on  $M$  CPUs to  $M$  instances of uniprocessor scheduling
  - Problem: system underutilisation



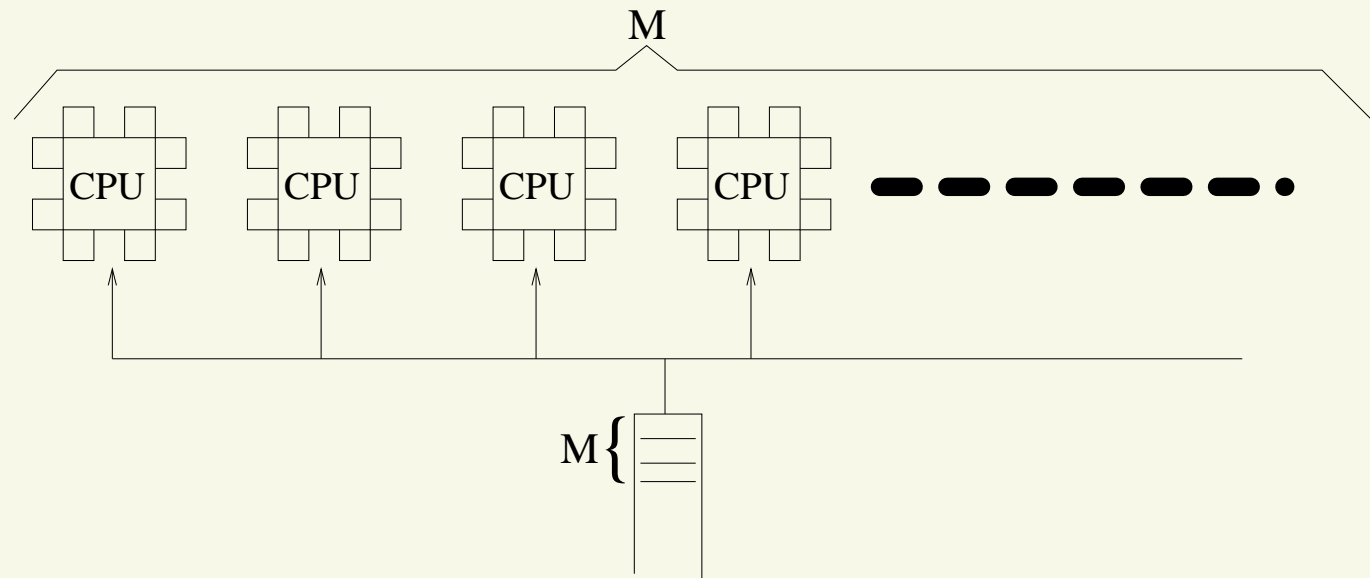
# Partitioned Scheduling - 2

- Reduce an  $M$  CPUs scheduling problem to  $M$  single CPU scheduling problems and a bin-packing problem
- CPU schedulers: uni-processor, EDF can be used
- Bin-packing: assign tasks to CPUs so that every CPU has load  $\leq 1$ 
  - Is this possible?
- Think about 2 CPUs with  $\{(6, 10, 10), (6, 10, 10), (6, 10, 10)\}$



# Global Scheduling

- One single task queue, shared by  $M$  CPUs
  - The first  $M$  ready tasks are selected
  - What happens using fixed priorities (or EDF)?
  - Tasks are not bound to specific CPUs
  - Tasks can often migrate between different CPUs
- Problem: schedulers designed for UP...



# Global Scheduling - Problems

- Dhall's effect:  $U^{lub}$  for global multiprocessor scheduling can be 1 (for RM or EDF)
  - Pathological case:  $M$  CPUs,  $M + 1$  tasks.  $M$  tasks  $(\epsilon, T - 1, T - 1)$ , a task  $(T, T, T)$ .
  - $U = M \frac{\epsilon}{T-1} + 1$ .  $\epsilon \rightarrow 0 \Rightarrow U \rightarrow 1$
- Global scheduling can cause a lot of useless migrations
  - Migrations are overhead!
  - Decrease in the throughput
  - Migrations are not accounted for...

# Global Scheduling for Soft Tasks

- Dhall's Effect  $\rightarrow$  global EDF and global RM have  $U^{lub} = 1$ 
  - With  $U > 1$ , deadlines can be missed
  - Global EDF / RM are not useful for hard tasks
- However, **global EDF** can be useful for scheduling **soft** tasks...
- When  $U \leq M$ , global EDF guarantees an **upper bound for the tardiness!**
  - Deadlines can be missed, but by a limited amount of time

# Multi-Core Root and Local Schedulers

- Two different cases: multiple physical CPUs and multiple virtual CPUs
  - The host has multiple CPUs / cores: global or partitioned root scheduler
  - The VM is composed by multiple (virtual) CPUs / cores: global or partitioned local scheduler
- Root scheduler: using a global or partitioned approach only changes the admission test
  - Partitioned scheduler:  $M$  instances of uni-processor admission test
  - Global scheduler: more complex admission test (multi-CPU TDA)
- Local scheduler: things are more complex...

# Multi-Core Scheduling in the Guest

- Guest scheduler (local scheduler): once a VM / component has been selected by the root scheduler, select a component's task
  - If the component runs on multiple (virtual) CPUs, can use a partitioned or global approach...
- Partitioned scheduling in the guest is easy
  - Every (virtual) CPU has its sbf; use it for schedulability analysis
- Global scheduling: on a physical machine, **the  $M$  highest priority tasks are scheduled**
  - VM: **the  $m'$  highest priority tasks of the guest must be scheduled on physical CPUs**
  - $m'$ : number of scheduled virtual CPUs

# Global Scheduling in the Guest

- Assume a component is scheduled on 2 virtual CPUs...
- ...And has 3 fixed priority ready tasks
- The guest/local scheduler selects the 2 highest priority tasks and schedules them
  - Now, assume that the root scheduler schedules one of the 2 virtual CPUs and preempt the other one...
  - What happens if the guest schedules the highest priority task on the virtual CPU that is not scheduled???
- **The guest/local scheduler must be aware of what the root scheduler is doing!!!**
- **If it is not, use partitioned scheduling in the guest!**

# Simpler Example

- Example to understand the issue:
  - Real-time tasks  $\tau_1 = (60, 100)$ ,  $\tau_2 = (10, 200)$
  - 2 vCPU threads, with (runtime, period) = (90, 100) and (40, 100)
  - PSF says the tasks are schedulable
- Scheduling  $\tau_1$  on vCPU 1 and  $\tau_2$  on vCPU 2, all deadlines are respected...
- ...But if  $\tau_1$  is scheduled on vCPU 2, it misses deadlines!
  - The guest scheduler must know the runtime and period associated to each virtual CPU
  - Or, it must be informed when the runtime of a virtual CPU has been consumed!

# Root Scheduler in Hypervisors

- Bare-metal hypervisor: implements a vCPU scheduler
  - Example: Xen provides an “RTDS” scheduler (deferrable server)
- Hosted hypervisor: use the host kernel scheduler
  - Example: using KVM, QEMU creates a thread for each virtual CPU (vCPU thread)
  - The `SCHED_DEADLINE` scheduling class can be used as a periodic server
- Not possible to use a global scheduler in the guest
- What to do if there is no scheduler (OS-level virtualization, etc...)?



# OS-Level Virtual Machines

- Do not virtualize the hardware, but the OS/kernel
  - Host kernel: virtualize its services to provide isolation among guests
- Based on *control groups* (cgroups) and *namespaces*
  - **namespaces**: isolate and virtualise system resources
  - **cgroups**: limit, control, or monitor resources used by groups of tasks
- No guest kernel  $\Rightarrow$  no separate local scheduler
- No vCPU thread to be scheduled
  - What to schedule? Containers/groups of tasks  $\rightarrow$  cgroups

# Container-Based Virtual Machines

- Modify `SCHED_DEADLINE` to schedule **groups of tasks** (cgroups)
  - Tasks inside the group: fixed priority scheduling
  - Based on Linux containers ← modifications of the control groups scheduler for real-time tasks
  - Can be used with `lxc`, Docker, etc...
- Reuse `SCHED_DEADLINE` code and control groups interface
  - Plug `SCHED_DEADLINE` (hard CBS algorithm) in real-time control groups

# Container-Based Real-Time Scheduling — 1

- Result: scheduling hierarchy
  - `SCHED_DEADLINE` (CBS) as a root scheduler
  - Fixed priorities as a second level scheduler
- Associate runtime and period to each virtual CPU of the VM
  - No runtime migration
  - Can use *cpusets* to control the number of virtual CPUs
- Real-Time virtual machine implementation based on containers!
  - Supports both partitioned and global scheduling

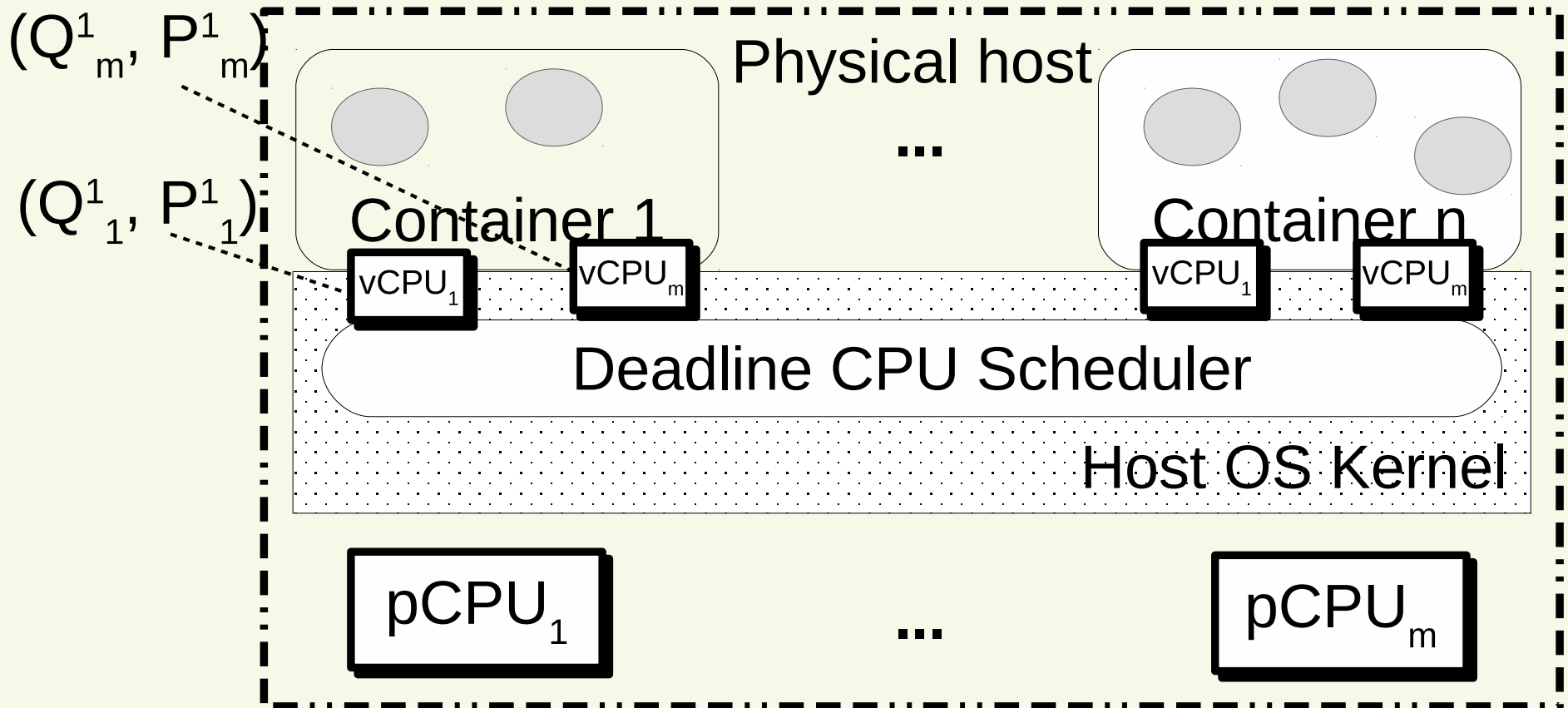
# Container-Based Real-Time Scheduling — 2

- Supports multiple CPUs
  - For the moment, same runtime / period on all the CPUs
  - Can be easily fixed / improved
- One single (host) scheduler: can support global (fixed-priority) scheduling in the guest
  - No need to implement communication between two different schedulers
  - When the runtime of a vCPU is 0, the scheduler can migrate tasks (push)

# Implementation

- Linux scheduling class: selects *entities*
  - Scheduling entities associated to tasks
  - `SCHED_DEADLINE` → dl entities
- Associate dl entities to queues of fixed priority tasks (rt runqueues)
  - A dl entity / rt runqueue per virtual CPU
  - When the dl entity is selected, get the highest priority task from the rt runqueue

# Scheduling Hierarchy



# Experimental Comparison

- VM with 4 virtual CPUs
  - Runtime  $10ms$  and period  $100ms$  on each virtual CPU
- CPU hungry real-time task in the guest
  - kvm-based VM: the task only executes for 10% of the CPU time **on one core**
  - lxc-based VM: the task only executes for 10% of the CPU time **on all the 4 cores**
- Because with kvm the guest has no way to know when the virtual CPU runtime is consumed (and to migrate the task)

# Combining KVM and cgroup Scheduling

- How to use global guest schedulers in KVM-based VMs?
  - Scheduler para-virtualisation: not so easy in this case...
  - Avoid invasive changes and reduce the overhead
- Idea: try to combine KVM vCPU scheduling with real-time control groups
  - Schedule kvm vCPU threads in a control group
  - Hierarchical container-based scheduler for the control group
  - Need to **pass information about thread priorities from guest to host**